

**DEPLOYMENT LOG for IceCube STRING # 48**Deployment Start: at 12:39 pm on 1/16/07Deployment End: at 9:34 on 1/16/07 9 hoursTarget depth (DOM60): **2450 m** Final depth: ~~9:26 pm~~
2455.8 m**Deployment Crew**

Position	First Shift	Second Shift
Shift lead	Tom Ham	A. Karle
DOM install 1 (high)	John Richards D	
DOM install 2 (low)	Greg Sullivan D	
DOM supply 1 / DOM install 3	Sven Lidstrom	
DOM supply 2 / floater		
Winch operator (cable & tower)	Dave Pernick	M. Kist / Ryan ^H / Albrecht K.
Notary (logbook & photos)	Justin Vanderbroucke	Justin / Michelangelo D.
PTS (monitoring / sensors)	Justin Vanderbroucke	
Support (optional)	Becky (GA)	C. Petterson

Time of shift change:

7 pm
↑

just for drop

Summary/Comments:

7 people

5 people

**Hole Handover**☐ Drill data reviewed☐ maximum drift in x: _____ ☐ plot☐ maximum drift in y: _____ ☐ plot☐ maximum depth: _____☐ minimum radius: _____ ☐ plot☐ plot of predicted radius vs depth and time☐ Hole dimensions verified

Time: _____

Drill Lead: _____
name / signature / dateDeployment Lead: _____
name / signature / date☐ Handover complete**Hole Logging**

(skip if not applicable)

☐ Logger drop started Time: _____ Speed: _____☐ Logging started Time: _____ Speed: _____☐ Logging ended Time: _____☐ Estimated hole lifetime: _____

▶ Must reach target depth by _____ on _____

**Deployment Startup**Time: 12:39 pm

- ☒ Cable winch anchored and ☒ operational
- ☒ Tower winch operational
- ☒ Tie off verified
- ☒ Yellow rope verified
- ☒ Deployment monitoring system (PTS) operational ☒ DDB# 3
- ☒ Pressure sensors on hand: Paro and Keller, with backups
- ☒ Laser ranger, tape measure (metric) on hand
- ☒ Bleeder string installed (on quad connectors inside cable reel drum)
- ☐ Uphole pressure system on hand: Setra sensor and cable
N/A
- ☒ DOMs placed in racks
- ☒ Weight stack on hand: weights (5) and 2 m cable
- ☒ 17 m string extension steel cable on hand
- Safety checks complete (☒ 1st shift ☐ 2nd shift)
 - ☒ ☐ Crew safety briefing
 - ☒ ☐ E-stop locations identified
 - ☒ ☐ TOS evacuation procedures reviewed
 - ☒ ☐ Mustering point identified
 - ☒ ☐ Snow mobile driver(s): _____
 - ☒ ☐ CPR trained: Sven, Tony, John
 - ☒ ☐ Food runners: _____

call galley at 65521

☒ End of Main Cable brought into TOS and secured**Cable end attachments**

- ☒ Measure well depth: 255 (ft) ~74 m
- ☒ Weights (5) attached
- ☒ Weight cable attached (weight stack complete)

Time: 1:00

Photos: DOM ids (☒ long ☒ short); connectors (☒ long ☒ short) 6P1305 Scram**DOM position 60**

(T, Long)

DOM id: TP 028

get by eliminating

☒ Bottom sh-☒ Top shacPhotos: ☐ wPayout: 0**DOM position**

(U, Short)

DOM id: UP 6P1286

ape

☒ Bottom shack☒ Top shackle co☒ Main cable endPhotos: ☒ phi orien

view

9-60): 18.5
(use laser ranger)**Breakout 30**Time: 1:42

Depth:

Payout 3.56**- LongDOM**☒ connector O-ring in place and ☒ lubed☒ breakout O-ring in place and ☒ lubed☐ connected

we take out the break out o-ring

- ShortDOM☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable**Paro**Serial #: 104664 Nipple ☒ on ☐ off☒ Connected ☒ Operational ☒ Air pressure [PSI]: 0.01☐ Cable mark: NA ☒ Distance to DOM59: 70 cm above

DOM 59

☒ All clear to lower cable ☺



Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)

DOM position 58DOM id: TP 6 P1231

(T, Long)

Cable mark: 19m☒ Bottom shackle connected☒ Top clutch connected at link # 18 $\Delta(58-59)$: ~~16.8~~ 16.8☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view**DOM position 57**load on 579.71DOM id: UP 6Y4376

(U, Short)

Cable mark: 3577092☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(57-58)$: 17.0☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view**Breakout 29**74/17 =5.17 = 854.17 = 68So @ DOM 55 Para hits

Time:

Now 2:00 PM**- LongDOM**☐ connector O-ring in place and ☐ lubed☒ breakout O-ring in place and ☐ lubed☐ connected

Last b/o _____

 Δt [min] _____

Depth:

Paro _____

Payout 52.82**- ShortDOM**☐ connector O-ring in place and ☐ lubed☒ breakout O-ring in place and ☐ lubed☐ connected☒ Loose pigtails taped to cable☐ All clear to lower cable ☺



Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)

DOM position 56DOM id: TP 6 P1215

(T, Long)

Cable mark: 53☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(56-57)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 55**DOM id: UP 6 P1290

(U, Short)

Cable mark: 69☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(55-56)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view**Breakout 28**~~Load cell = 171~~

Time:

Now 2:10Last b/o Δt [min]

Depth:

Paro 10.53Payout 69.96**- LongDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected**- ShortDOM**☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

load = 754

Antarctic Treaty inspectors (D V's visit ~ 5 min.)

Payout was 15.86 when Dom 60 @ 17.5 \rightarrow should have been 17.5 so when☒ All clear to lower cable ☺~~change~~So when Dom 60 was at top, payout was ~~Dom 60 was~~ 15.95 - 17.5 = -1.6 changed. 6/37

Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)**DOM position 54**DOM id: TP 6 P 12 17

(T, Long)

Cable mark: 87☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(54-55)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view**DOM position 53**DOM id: UP 644 362

(U, Short)

Cable mark: 1047543 8☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(53-54)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 27**

Time:

- LongDOM☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☐ connectedNow ~~8:00~~ 2:28Last b/o Δt [min]

Depth:

Paro ~~800~~ 128Payout 125

(after started drop)

- ShortDOM☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☐ connected☒ Loose pigtails taped to cable☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 52**DOM id: TP 6P 1243

(T, Long)

Cable mark: 121☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(52-53)$: 16.9☐ Bow OK \rightarrow ☐ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 51**DOM id: UP 6H7510

(U, Short)

Cable mark: 140☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(51-52)$: 17.0☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view**Breakout 26**

Time:

Now 2:37**- LongDOM**Last b/o ☒ connector O-ring in place and ☐ lubed Δt [min] ☒ breakout O-ring in place and ☐ lubed

Depth:

☒ connectedParo 157Payout 155**- ShortDOM**☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cableload = 753.6☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 50**DOM id: TP 6 Y4253

(T, Long)

Cable mark: 0155☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(50-51)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view☐ Curved distance around DOM: _____ ☐ Vertical distance: _____**DOM position 49**DOM id: UP 6 Y4278

(U, Short)

Cable mark: 017175419☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(49-50)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view☐ Curved distance around DOM: _____ ☐ Vertical distance: _____**Breakout 25**

Time:

- LongDOM☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connectedNow 2:47

Last b/o _____

 Δt [min] _____

Depth:

Paro 192Payout 190**- ShortDOM**☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

payout seems to be
slipping somewhat

☒ All clear to lower cable ☺



Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)

DOM position 48DOM id: TP 647501

(T, Long)

Cable mark: 189☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(48-49)$: 17.0☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 47**DOM id: UP 6P132

(U, Short)

Cable mark: 206☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(47-48)$: 16.9☐ Bow OK \rightarrow ☐ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 24**

Time:

Now 2:55**- LongDOM**☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected

Last b/o _____

 Δt [min] _____Depth: 225.9

Paro _____

Payout 223.5**- ShortDOM**☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 46**DOM id: TP 6Y4227

(T, Long)

Cable mark: 223

77172

☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(46-47)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 45**DOM id: UP 6P1270

(U, Short)

Cable mark: 239☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(45-46)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 23**

Time:

Now 3:04 pm**- LongDOM**

Last b/o _____

☒ connector O-ring in place and ☐ lubed Δt [min] _____☐ breakout O-ring in place and ☐ lubed

Depth:

☒ connectedParo 260Payout 257**- ShortDOM**☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cableload 840 913☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 44**

(T, Long)

Cable mark: 257DOM id: TP 6P1299☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(44-45)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 43**

(U, Short)

Cable mark: 273DOM id: UP 6P1260☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(43-44)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☐ whole view**Breakout 22**

*This DOM hit the hole collar
Dip hard before going down.*

Time:

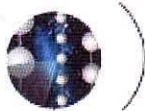
Now 3:13**- LongDOM**

Last b/o _____

☒ connector O-ring in place and ☒ lubed Δt [min] _____☒ breakout O-ring in place and ☐ lubed

Depth:

☐ connectedParo 294.0Payout 290.1**- ShortDOM**☒ connector O-ring in place and ☒ lubed☒ breakout O-ring in place and ☐ lubed☐ connected☒ Loose pigtails taped to cable☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 42**DOM id: TP 6Y4473

(T, Long)

Cable mark: 291☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(42-43)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 41**DOM id: UP 6P1226

(U, Short)

Cable mark: 0308☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(41-42)$: 16.8☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 21***inspected winch*

Time:

Now 3:26**- LongDOM**

Last b/o _____

☒ connector O-ring in place and ☒ lubed Δt [min] _____☐ breakout O-ring in place and ☐ lubed

Depth:

☒ connectedParo 338Payout 334**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable*928 load*☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 40**DOM id: TP 6 P1303

(T, Long)

Cable mark: 325☒ Bottom shackle connected☒ Top clutch connected at link # 26 $\Delta(40-41)$: 17.0☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 39**DOM id: UP 6 P1250

(U, Short)

Cable mark: 342☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(39-40)$: 17.0☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 20**

Time:

Now 3:35**- LongDOM**Last b/o ☒ connector O-ring in place and ☐ lubed Δt [min] ☐ breakout O-ring in place and ☐ lubed

Depth:

☒ connectedParo 369Payout 366**- ShortDOM**☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cableLoad = 971☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☒ long ☐ short)**DOM position 38**DOM id: TP 6 P1229

(T, Long)

Cable mark: 359☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(38-39)$: 16.9☐ Bow OK \rightarrow ☐ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 37**DOM id: UP 6 P1296

(U, Short)

Cable mark: 376☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(37-38)$: 17.0☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 19**

Time:

- LongDOM☒ connector O-ring in place and ☒ lubed☐ ~~breakout O-ring in place and~~ ☐ lubed☒ connectedNow 3:44Last b/o 3:28 Δt [min] 16

Depth:

Paro 398Payout 394**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ ~~breakout O-ring in place and~~ ☐ lubed☒ connected☒ Loose pigtails taped to cableLoad = 980 lbs☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☐ short); connectors (☐ long ☐ short)**DOM position 36**DOM id: TP 6Y4469

(T, Long)

Cable mark: 393

77258

☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(36-37)$: 16.9☐ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view

bow = 2.43

Bow measurement: straight = 2.41 $\rightarrow \Delta = 2$ cm**DOM position 35**DOM id: UP 6Y4466

(U, Short)

Cable mark: 410

77216

☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(35-36)$: 17.0☐ Bow OK \rightarrow ☐ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view~~2.43 = 2.41 = 2 cm~~**Breakout 18**

Time:

Now 4:00

- LongDOM

☒ connector O-ring in place and ☐ lubed

Last b/o _____

~~☐ breakout O-ring in place and ☐ lubed~~ Δt [min] _____☒ connected

Depth:

Paro 441Payout 436

- ShortDOM

☒ connector O-ring in place and ☐ lubed~~☐ breakout O-ring in place and ☐ lubed~~☒ connected

970

Load - ~~1000~~ lbs☒ Loose pigtails taped to cable☒ Put two Kellers (one is for backup) in bucket of water/ice mix☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 34**DOM id: TP 6 P1249

(T, Long)

Cable mark: 427

- ☒ Bottom shackle connected
- ☒ Top clutch connected at link # 20
- ☐ Bow OK → ☒ clutch zip tied

Photos: ☒ phi orientation ☒ whole view $\Delta(34-35)$ 16.5
triple-checked**DOM position 33**DOM id: UP 6 P1294

(U, Short)

Cable mark: 444

- ☒ Bottom shackle connected
- ☒ Top clutch connected at link # 20
- ☐ Bow OK → ☒ clutch zip tied

Photos: ☒ phi orientation ☒ whole view $\Delta(33-34)$ 16.9**Breakout 17**

Time:

Now 4:09

Last b/o _____

 Δt [min] _____

Depth:

Paro 465Payout 462**- LongDOM**

- ☒ connector O-ring in place and ☒ lubed
- ☒ ~~breakout O-ring in place and~~ ☐ ~~lubed~~
- ☒ connected

- ShortDOM

- ☒ connector O-ring in place and ☒ lubed
- ☒ ~~breakout O-ring in place and~~ ☐ ~~lubed~~
- ☒ connected

☒ Loose pigtails taped to cable

1058 load

☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 32**DOM id: TP 6P1425

(T, Long)

Cable mark: 461☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(32-33)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view \uparrow **DOM position 31**

(U, Short)

Cable mark: 478☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(31-32)$: 16.9
6P1498☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 16**

Time:

- LongDOM☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connectedNow 4:20Last b/o Δt [min]

Depth:

Paro 494Payout 495**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

1036 load

☒ All clear to lower cable ☺



Photos: DOM ids (☒ long ☐ short); connectors (☐ long ☐ short)

DOM position 30DOM id: TP 6P1261

(T, Long)

Cable mark: 495☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(30-31)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 29**DOM id: UP 6P1506

(U, Short)

Cable mark: 512☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(29-30)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view**Breakout 15**

Keller @ DOM 29

 $74 \text{ m} = 4.17 + 6$

Time:

- LongDOM

☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connectedNow 4:40

Last b/o

 Δt [min]

Depth:

Paro 545Payout 541

- ShortDOM

☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

actually, we didn't see a thermistor. estimated where it would be beneath the tape, it did change reading when connected

but now zero temp. reading

who knows?

Thermistor☒ Present ☒ Distance to DOM29: 80 m**Keller**☒ Connected ☐ Operational ☐ Air pressure [PSI]: -12Ser.#: 0606736 ☒ Cable mark: 513 ☒ Distance to DOM29: 1.55 m

Fluctuating

- 931.46847 ☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☐ short); connectors (☐ long ☐ short)**DOM position 28**DOM id: TP 6P1505

(T, Long)

Cable mark: 529☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(28-29)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 27**

(U, Short)

Cable mark: 54DOM id: UP 6P1456☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(27-28)$: 17.0☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view**Breakout 14**

Time:

- LongDOM☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

1080 load

Now _____

Last b/o _____

 Δt [min] _____

Depth:

Paro 569Keller 565Payout 570toga then
delayed☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 26**DOM id: TP 6P 1465

(T, Long)

Cable mark: 563☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(26-27)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 25***broken connector*DOM id: UP 6P 1282

(U, Short)

Cable mark: 580☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(25-26)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view*redid taping, 1st time not enough clearance*
*watch for Keller during 25 drop \checkmark hit water***Breakout 13**

Time:

Now 5:02

- LongDOM

Last b/o ☒ connector O-ring in place and ☒ lubed Δt [min] ☐ breakout O-ring in place and ☐ lubed

Depth:

☒ connectedParo 616

- ShortDOM

Keller 90☒ connector O-ring in place and ☒ lubedPayout 612☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable☐ All clear to lower cable ☺

Photos: DOM ids (☐ long ☒ short); connectors (☐ long ☐ short)**DOM position 24**DOM id: TP 6P1355

(T, Long)

Cable mark: 597☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(24-25)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 23**DOM id: UP 6P1508

(U, Short)

Cable mark: 614☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(23-24)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 12**

Time:

- LongDOM☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cableNow 5:14Last b/o Δt [min]

Depth:

Paro 635Keller Payout 631

Keller to DOM 60:

 $0.8 + \text{~~300~~} 31.17$ $= \text{~~196.8~~} 0.8 + 17.30 + 17$ $= 17.8 + 300 + 210$ $= 527.8$ just added the offset
in software

10

☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☐ short); connectors (☐ long ☐ short)**DOM position 22**DOM id: TP 6P1517

(T, Long)

Cable mark: 631☒ Bottom shackle connected☒ Top clutch connected at link # 20 $\Delta(22-23)$: 17.0☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 21**DOM id: UP 6P1516

(U, Short)

Cable mark: 648☒ Bottom shackle connected☒ Top clutch connected at link # 19

switching from link
steel cables of DOMs have not
tight enough; DOM angle and
bow also

 $\Delta(21-22)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 11**

Time:

Now 5:26Last b/o Δt [min]

Depth:

Paro 670Keller 676Payout 665**- LongDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable1210 load

From now on,
measuring while stoppped,
before beginning drop.

☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☐ short); connectors (☐ long ☐ short)**DOM position 20**DOM id: TP 6P1515

(T, Long)

Cable mark: 665☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(20-21)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view☒ Curved distance around DOM: _____ ☐ Vertical distance: _____*Keller started oscillating more***DOM position 19**DOM id: UP 6P1288

(U, Short)

Cable mark: 682☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(19-20)$: 17.0☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view☐ Curved distance around DOM: _____ ☐ Vertical distance: _____**Breakout 10**

Time:

Now 5:36**- LongDOM**

Last b/o _____

☒ connector O-ring in place and ☒ lubed Δt [min] _____☐ breakout O-ring in place and ☐ lubed

Depth:

☒ connectedParo 704Keller 703**- ShortDOM**Payout 700☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

1239 load
after adding DOM60 - Keller
distance, Keller has taken ~4 DOMs to relax
to be consistent with Paro and payout

☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); ~~connectors~~ (☐ long ☐ short)**DOM position 18**DOM id: TP 6P1513

(T, Long)

Cable mark: 699☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(18-19)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 17**DOM id: UP 6P1210

(U, Short)

Cable mark: 716☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(17-18)$: 16.9☐ Bow OK \rightarrow ☐ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 9**

Time:

- LongDOM☒ connector O-ring in place and ☒ lubed☐ ~~breakout O-ring in place and~~ ☐ lubed☒ connected**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ ~~breakout O-ring in place and~~ ☐ lubed☒ connected☒ Loose pigtails taped to cableNow 5:45Last b/o Δt [min]

Depth:

Paro 738Keller 748Payout 7341326 load☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 16**DOM id: TP 6P1307

(T, Long)

Cable mark: 733☒ Bottom shackle connected☒ Top clutch connected at link # 19☒ Bow OK → ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view $\Delta(16-17)$: 16.9

2.42 = bow length

2.41 = "straight" length

DOM position 15DOM id: UP 6H7516

(U, Short)

Cable mark: 750☒ Bottom shackle connected☒ Top clutch connected at link # 19☒ Bow OK → ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view $\Delta(15-16)$: 17**Breakout 8**

Time:

Now 5:56**- LongDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected

Last b/o _____

 Δt [min] _____

Depth:

Paro 772Keller 780Payout 767**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

1300 load

☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☐ short); connectors (☐ long ☐ short)**DOM position 14**DOM id: TP 6P1435

(T, Long)

Cable mark: 767☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(14-15)$: 17.0☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 13**DOM id: UP 6P 1460

(U, Short)

Cable mark: 784☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(13-14)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 7**

Time:

Now 6:09**- LongDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connectedLast b/o Δt [min]

Depth:

Paro 807Keller 815Payout 802**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

1340 load

changed DOM60 - Paro dist. from 17.7
to 19.2 after realizing actual $\Delta 60-59 = 18.5$
not 17also added 1.5 to
Keller - DOM60 dist.☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 12**DOM id: TP 6 P1467

(T, Long)

Cable mark: 801☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(12-13)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 11**DOM id: UP 6 P1474

(U, Short)

Cable mark: 818☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(11-12)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 6**

Time:

- LongDOM☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected**- ShortDOM**☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable

1399 load

Now 6:20 PM

Last b/o _____

 Δt [min] _____

Depth:

Paro 842Keller 848Payout 835☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 10**DOM id: TP 6P1213

(T, Long)

Cable mark: 835☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(10-11)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 9**DOM id: UP 6P1344

(U, Short)

Cable mark: 852☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(9-10)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 5**

Time:

- LongDOM☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☐ connected**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☐ connected☒ Loose pigtails taped to cable

~~used 0.8~~ should have been ~~1.6~~ 1430 load

Now 6:33Last b/o Δt [min]

Depth:

Paro 876Keller 880Payout 869☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☐ short); connectors (☐ long ☐ short)**DOM position 8**DOM id: TP 6 P 1429

(T, Long)

Cable mark: 869☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(8-9)$: 17.0☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 7**DOM id: UP 6 P 1436

(U, Short)

Cable mark: 886☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(7-8)$: 17.0☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☐ phi orientation ☐ whole view**Breakout 4***3 wire cables in wrong order
 \rightarrow fixed*

Time:

Now 6:47Last b/o Δt [min]

Depth:

Paro 910Keller 919Payout 904**- LongDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable*1428 load**changed keller offset by
a couple meters reflecting**① 18.5 actual 260-59**② used Paro-DOM instead of keller-DOM
mistake*☐ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 6**DOM id: TP 6P1273

(T, Long)

Cable mark: 903

- ☒ Bottom shackle connected
- ☒ Top clutch connected at link # 19
- ☒ Bow OK → ☒ clutch zip tied

 $\Delta(6-7)$: 17.0Photos: ☒ phi orientation ☒ whole view**DOM position 5**DOM id: UP 6H7518

(U, Short)

Cable mark: 920

- ☒ Bottom shackle connected
- ☒ Top clutch connected at link # 19
- ☒ Bow OK → ☒ clutch zip tied

 $\Delta(5-6)$: 17.0Photos: ☒ phi orientation ☒ whole view**Breakout 3**

Time:

- LongDOM

- ☐ connector O-ring in place and ☐ lubed
- ☐ breakout O-ring in place and ☐ lubed
- ☒ connected

Now 6:58 pmLast b/o Δt [min]

Depth:

Paro 944.3Keller 952.0Payout 938.0**- ShortDOM**

- ☐ connector O-ring in place and ☐ lubed
- ☐ breakout O-ring in place and ☐ lubed
- ☒ connected

☒ Loose pigtails taped to cable

1427 load?

☒ All clear to lower cable ☺

Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)**DOM position 4**DOM id: TP 6P1473

(T, Long)

Cable mark: 337 937

- ☒ Bottom shackle connected
- ☒ Top clutch connected at link # 19
- ☒ Bow OK → ☒ clutch zip tied

 $\Delta(4-5)$: 17.0Photos: ☒ phi orientation ☒ whole view**DOM position 3**DOM id: UP 6P1468

(U, Short)

Cable mark: 954

- ☒ Bottom shackle connected
- ☒ Top clutch connected at link # 19
- ☒ Bow OK → ☒ clutch zip tied

 $\Delta(3-4)$: 17.0Photos: ☒ phi orientation ☒ whole view**Breakout 2**

Time:

- LongDOM

- ☒ connector O-ring in place and ☒ lubed
- ~~☐ breakout O-ring in place and ☐ lubed~~
- ☒ connected

Now 7:07

Last b/o _____

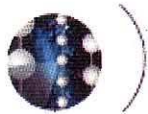
 Δt [min] _____

Depth:

Paro 979Keller 995Payout 972**- ShortDOM**

- ☒ connector O-ring in place and ☒ lubed
- ~~☐ breakout O-ring in place and ☐ lubed~~
- ☒ connected

☒ Loose pigtails taped to cable☒ All clear to lower cable ☺



Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)

DOM position 2DOM id: TP 6H7513

(T, Long)

Cable mark: 971☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(2-3)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**DOM position 1**DOM id: UP 6P1248

(U, Short)

Cable mark: 988☒ Bottom shackle connected☒ Top clutch connected at link # 19 $\Delta(1-2)$: 16.9☒ Bow OK \rightarrow ☒ clutch zip tiedPhotos: ☒ phi orientation ☒ whole view**Breakout 1**

Time:

- LongDOM☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connectedNow 7:18Last b/o Δt [min]

Depth:

Paro 1013Keller 1020Payout 1006**- ShortDOM**☒ connector O-ring in place and ☒ lubed☐ breakout O-ring in place and ☐ lubed☒ connected☒ Loose pigtails taped to cable**No second Paro no more...**☒ Group photo☒ All clear to lower cable ☺

**Uphole Pressure Sensor (Setra)**

After DOM1 is safely under the surface (> 50 m)

Time: _____

- ☐ Stop the cable winch
- ☐ Lower Setra pressure sensor into hole
- ☐ Distance to Setra from floor: _____
- ☐ Setra readout verified with monitoring system
- ☐ Well depth from Setra: _____
- ☐ Well depth from laser: _____

If the two well depth measurements agree:

- ☐ Switch to Setra well depth in monitoring system

Time: _____

Now the String Drop begins



String Drop

*PTS Guru can stop on a dime.

The target depth is **2450 m**

However, shift lead Karle requested a deeper string ≈ 2455 m due to "better ice."

☐ Switch cable winch to computer control

☒ Speed: 0.39 Time: 7:43 Depth: 1118

☒ Speed: .37 Time: 7:58 Depth: 1445

☒ Speed: .23 Time: 8:53 Depth: 2356

☒ Speed: .21 Time: 8:59 Depth: 2420

☐ Speed: _____ Time: _____ Depth: _____

☐ Speed: _____ Time: _____ Depth: _____

actually we're doing fewer points but with a stop at each Para valve exact \rightarrow syncing

Depth Monitoring

(log on the fly - do not stop for this)

Depth by Paro ¹	Time	Well depth ¹	Depth by cable marks ²	Depth by Payout ¹	Δ depth P-K ¹	
1000 m	<u>7:22</u>	<u>65.6</u>	<u>992+16.5</u>	<u>1011</u>	<u>←</u>	not sync'd
1500 m	<u>8:01</u>	<u>65.85</u>	<u>1008.5</u>	<u>1501.8</u>	<u>-20</u>	0.5
2000 m	<u>8:29</u>	<u>65.2</u>	<u>1483+16.5</u>	<u>2000.9</u>	<u>-12</u>	4.5
2100 m			<u>1978+16.5</u>			
2200 m	<u>8:42</u>	<u>65.2</u>	<u>2178+16.5</u>	<u>2200</u>	<u>-16</u>	5.5
2300 m			<u>2194.5</u>			
2400 m	<u>8:57</u>	<u>65.0</u>	<u>2376.5+16.5</u>	<u>2399</u>	<u>-16</u>	7.0

¹Read off monitoring screen

²Cable mark offset = 2 m (at DOM59) - 17 m = -16.5 (at DOM60)
(from p.4) 18.5

☒ Switch to manual control @ 2400 m

☐ Well depth

@ 2420:

@ 2440:

Stopped at 2425.5 m
+16.5 = 2442 m
by Paro 2
stretch = 7.5
Now anchoring

☒ Position string at target depth of **2450 m**

Time: 9:26

☒ String secured with Yale grip and anchor chain

Time: 9:26



Absolute depth with bottom Paro (depth in *meters* and pressure in *PSI*)

☒ Distance from Paro to DOM60:

$$d_{\text{Paro-DOM59}} = \underline{0.7} \text{ (from p. 4)}$$

$$d_{\text{Paro-DOM60}} = (d_{\text{Paro-DOM59}} + \underline{17}) \text{ m} = \underline{19.2} \leftarrow \text{insert below}$$

18.5

☐ Convert Paro pressure to string depth:

$$K = 3.78151 \cdot 10^{-6} \text{ /PSI (compressibility of aerated water)}$$

(use 6 decimals for exp's)

Ambient pressure (from p. 4): $P_0 = \underline{\hspace{2cm}} \text{ PSI} \rightarrow \exp(-KP_0) = \underline{\hspace{2cm}}$

Pressure reading (from screen): $P = \underline{\hspace{2cm}} \text{ PSI} \rightarrow \exp(-KP) = \underline{\hspace{2cm}}$

Subtract exponentials \rightarrow $= \underline{\hspace{2cm}}$
 $\times 1.85947 \cdot 10^5$

Paro depth in water \rightarrow $= \underline{\hspace{2cm}} \text{ m}$

Add distance to DOM60 (above) \rightarrow $+ \underline{\hspace{2cm}} \text{ m}$

Add well depth \rightarrow $+ \underline{\hspace{2cm}} \text{ m}$

Depth of bottom DOM \rightarrow $= \underline{\hspace{2cm}} \text{ m}$

Final depth estimates

←----- read off deployment screen -----→

Time:	Paro	Keller	Payout	Cable marks
Reading	<u>3405</u> PSI	<u>2670</u> PSI	<u>2453.2</u> m	<u>2431.6</u> m
Offset	<u>10.53</u> PSI	<u>-11.4</u> PSI	<u>-1.6</u> m	<u>-16.5</u> m
Well depth	<u>64.9</u> m	<u>530.1</u> m	This space is intentionally left blank	
Dist. to DOM60	<u>19.2</u> m	<u>530.1</u> m		
DEPTH (DOM60)	<u>2455.8 *</u>	<u>2470</u>	<u>2454.8</u>	<u>2448.1</u>

$$\text{stretch} =$$

$$2455.8 - 2448.1$$

$$\text{stretch} = \underline{7.7 \text{ m}}$$

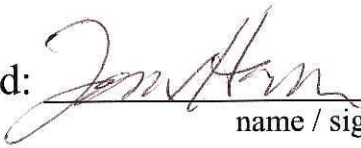

Time: 9:26 pm

$$\Delta(\text{payout} - \text{Paro}) = \underline{-1 \text{ m}}$$

Final depth (DOM60): 2455.8 * (see prev. page)

**Deployment Closeout**

- ☒ Log entries complete
- ☒ String safely secured
- ☒ Hole covered and secured
- ☐ Equipment safely shutdown and secured
- ☐ Deployment data OK (in database)
- ☐ Site cleanup
- ☐ Deployment crew dismissed
- ☐ String deployment complete

Time: 9:34 Date: 1/16/06Shift Lead: 
name / signatureLogger: _____
name / signaturePTS Lead:  / Justin Vandembroucke
name / signatureDeployment Manager:  / Tom Ham
name / signatureSafety Officer: _____
name / signatureIceCube On-ice Lead: _____
name / signature



IceCube Deployment Monitoring Check Sheet (IDMCS)

Version 4.0

December 12, 2006

Kurt Woschnagg, UCB

General instructions

- ▶ Read through this entire document before deployment starts.
- ▶ Deployment monitoring is done with a computer (housed in the TOS) running drill/deployment monitoring software (by Chuck Rentmeesters) with a GUI for readout and manual inputs. All deployment sensor data and manual inputs are logged and saved on disk by this system.
- ▶ For each manual entry into the monitoring interface (marked **ENTER** below), also make a note in the logbook (marked *Logbook* below).
- ▶ For each entry in the logbook, include time and name (initials).
- ▶ Write down as much useful information you can think of (it *will* all be needed sooner or later).

Measurement instructions

- ▶ All vertical measurements are relative to the floor of the tower (not the lip of the kick board).
 - Measure well depth from this level.
 - Take cable mark readings at this level.
- ▶ The location of a DOM on a string (for distance measurements) is defined as the position of the center of the sphere (at the equator defined by the harness).
- ▶ When taking a cable mark reading, estimate the location to nearest cm (0.01 m) with closest cable marks and tape measure.
- ▶ The location of a Paro is defined at the bottom of its body (at the little hole with the nipple).
- ▶ The location of a Keller is defined at the row of holes in the black plastic nose cap.
- ▶ The distance between a pressure sensor and the nearest DOM is positive/negative if the unit is above/below the DOM.
- ▶ Well depth is measured with a laser ranger (if possible), or with a tape measure (if not).
- ▶ The unit used for all distances and depths during deployment is **meters**.

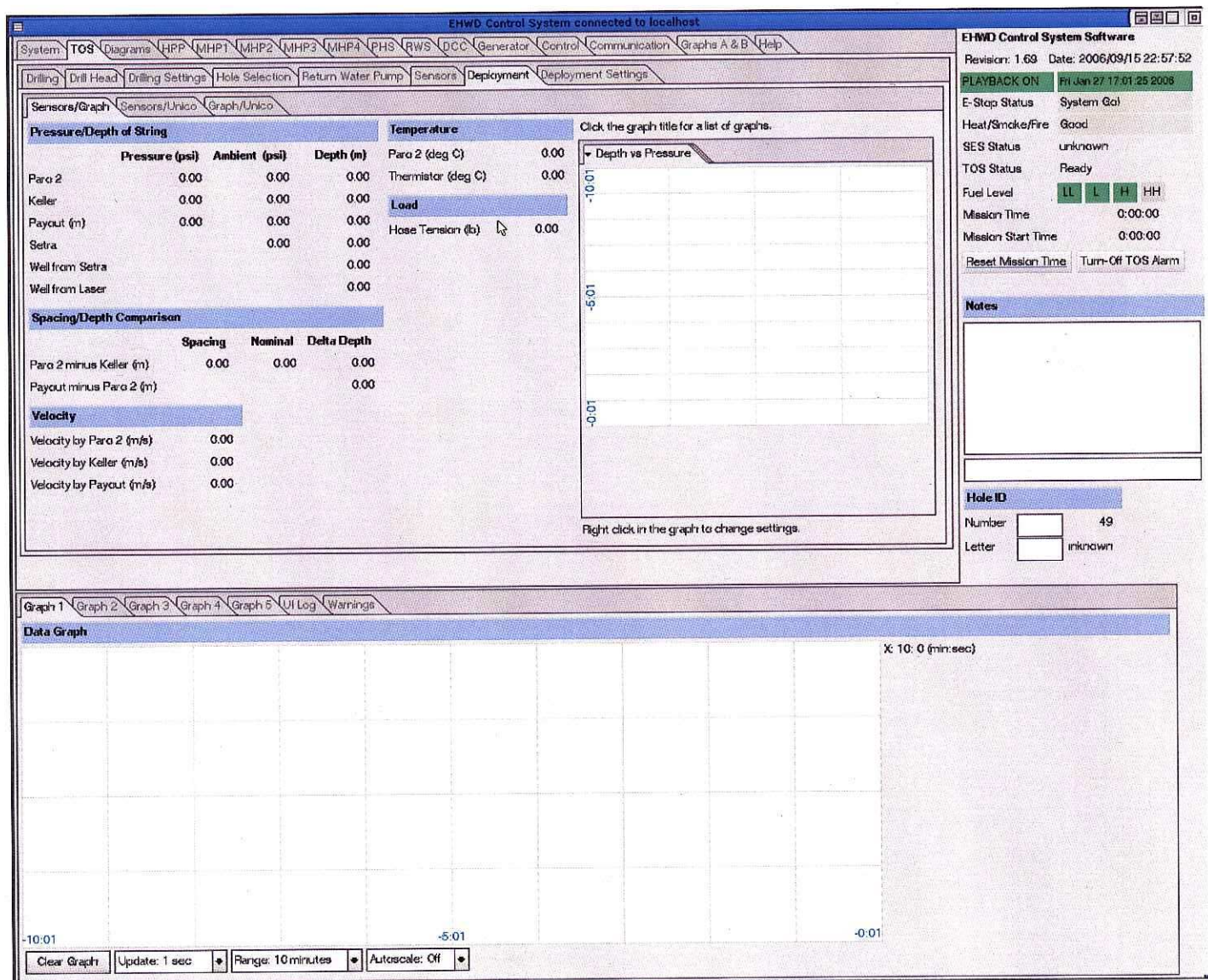


Screen Tab: TOS ► Deployment

► Sensors/Graph

This is the main tab used during deployment monitoring. No input required on this tab.

Pressure/Depth of String	Current and ambient (air) pressures, and the corrected depths at DOM60.
Spacing/Depth Comparison	Difference in depth from pressure data. <i>Should be stable during deployment!</i>
Velocity	The deployment velocity calculated from recent pressure/payout readings.
Temperature	Temperature readings.
Load	Cable tension from load cell data.

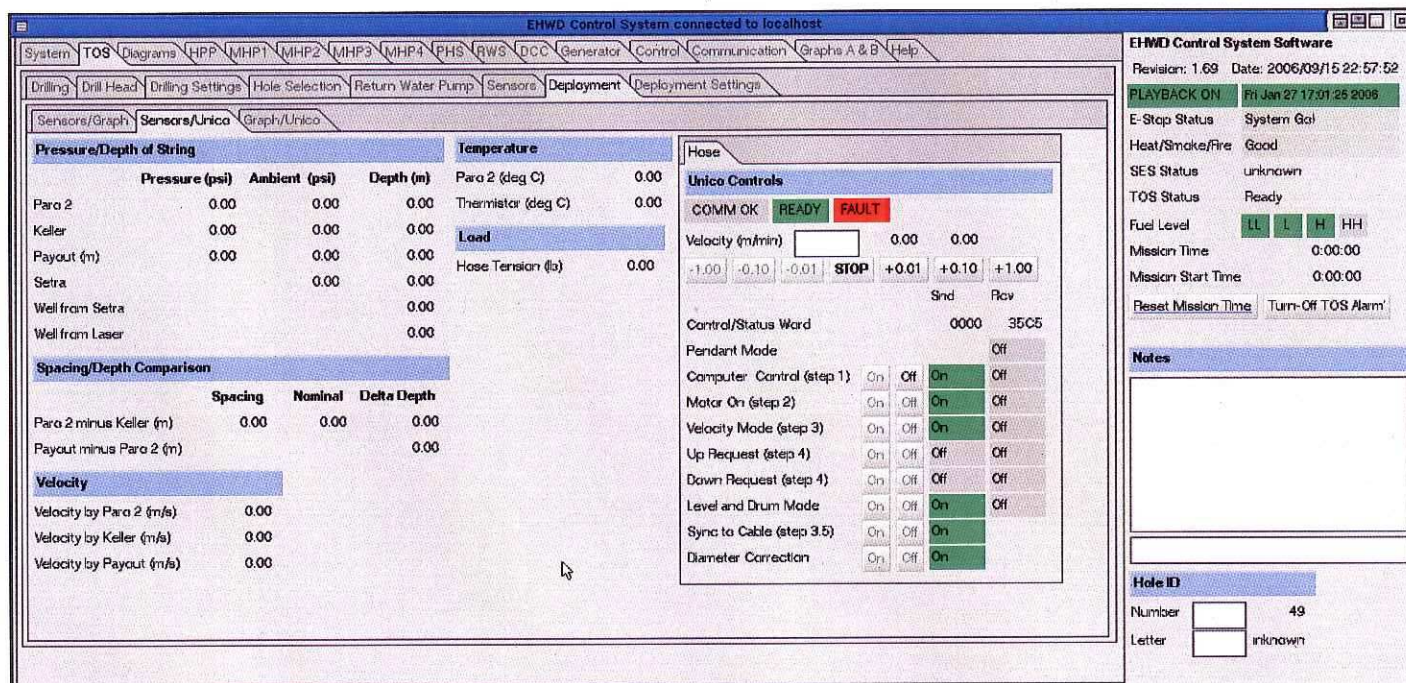




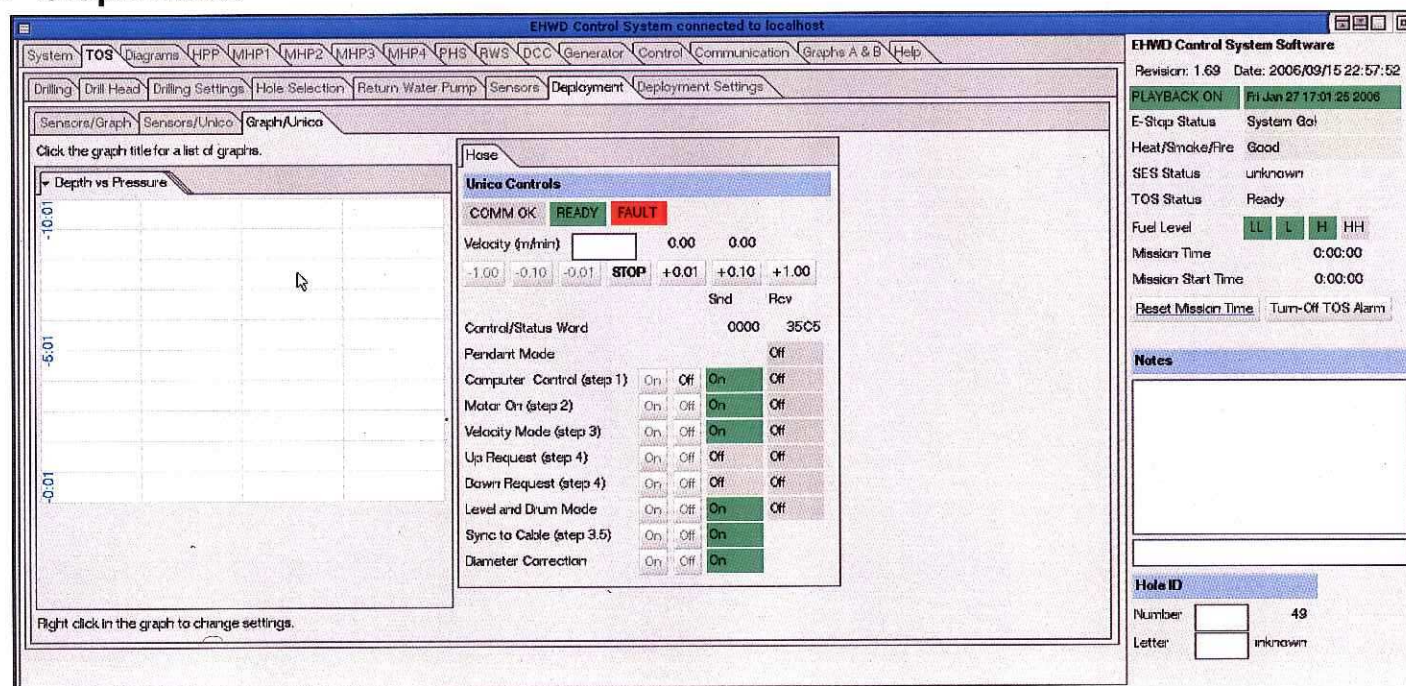
Screen Tab: TOS ► Deployment

► Sensors/Unico

This tab has the same data display as the main Sensors/Graph tab above, but instead of the graph window this tab has the controls for the Unico drive which controls the winch.



► Graph/Unico





Screen Tab: TOS ► Deployment Settings

► Settings

This is the main tab for entering information that is needed for a correct depth calibration of the pressure data. Make sure you understand what all the entries mean before deployment starts.

Tower Mode	Click on "Deployment".
Deployment Events	Click the appropriate button when one of the predefined events occurs (see list below).
DDB Mode	Select the correct DDB ID before deployment startup (needed for Keller calibration).
Payout at Tower	Reset payout when bottom DOM is at tower floor level.
Well Depth Selection	Select source of well depth used in depth calculation.
Ambient Pressures	Press "Get" when pressure sensor is attached to cable, or enter reading at that time.
Nominal Spacing	Enter calculated distance between Paro and Keller.
Distances	Enter calculated distances between Paro/Keller and DOM60, and well depth.
Setra Depth Calib.	Enter measured length of Setra cable, from floor to sensor.
Alarms	Set values for which alarm is to be sounded (optional).

The screenshot shows the 'EHWD Control System' software interface. The top menu bar includes 'System', 'TOS', 'Diagrams', 'HPP', 'MHP1', 'MHP2', 'MHP3', 'MHP4', 'PHS', 'RWS', 'DCC', 'Generator', 'Control', 'Communication', 'Graphs A & B', and 'Help'. The 'TOS' menu is open, showing 'Drilling', 'Drill Head', 'Drilling Settings', 'Hole Selection', 'Return Water Pump', 'Sensors', 'Deployment', and 'Deployment Settings'. The 'Deployment Settings' tab is active, showing a 'Settings' window with 'Keller Calibration' selected. The 'Settings' window has several sections: 'Tower Mode' (unknown, buttons for Drilling and Deployment), 'Deployment Events' (unknown, buttons for Startup, Paro Attached, Paro In Water, Keller Attached, Keller In Water, String Drop, Complete), 'DDB Mode' (ID Z: unknown, Status: Ready, buttons for unknown, DDB01, DDB02, DDB03, DDB04), 'Payout at Tower From Hose' (table with Start, Current, Difference columns), 'Well Depth Selection' (Using: Laser Well Depth, buttons for Use Laser Well Depth, Use Setra Well Depth), 'Ambient Pressures' (Paro 2 (psi), Keller (psi), Setra (psi) with Get buttons), 'Nominal Spacing Values' (Paro 2 to Keller (m)), 'Distances' (From Paro 2 to bottom DOM (m), From Keller to bottom DOM (m), Laser Well Depth (m)), 'Setra Depth Calibration' (Floor to Setra Length (m), Water Compressability Factor), and 'Alarms' (Paro 2 minus Keller (m), Depth 1 (m), Depth 2 (m), Depth 3 (m)). On the right, the 'EHWD Control System Software' panel shows 'Revision: 1.69', 'Date: 2006/09/15 22:57:52', 'PLAYBACK ON' (button), 'E-Stop Status' (System Go!), 'Heat/Smoke/Fire' (Good), 'SES Status' (unknown), 'TOS Status' (Ready), 'Fuel Level' (LL, L, H, HH), 'Mission Time' (0:00:00), 'Mission Start Time' (0:00:00), 'Reset Mission Time' (button), and 'Turn-Off TOS Alarm' (button). The 'Notes' section is empty. The 'Hole ID' section shows 'Number' (49) and 'Letter' (unknown).

Deployment Events

- ☐ **Startup** Click when the deployment begins.
- ☐ **Paro Attached** Click when the Paro is attached to the breakout and starts sending data.
- ☐ **Paro In Water** Click when the Paro reaches the water.
- ☐ **Keller Attached** Click when the Keller is attached to the breakout and starts sending data.
- ☐ **Keller In Water** Click when the Keller reaches the water.
- ☐ **String Drop** Click when the String Drop phase begins, after all DOMs have been attached.
- ☐ **Complete** Click when the deployment ends (string is secured, etc).



Screen Tab: TOS ► Deployment Settings

► Keller Calibration

On this tab you select the Keller ID by clicking on the appropriate button. The correct (pre-programmed) calibration constants will then be used for the Keller pressure reading.

The screenshot shows the 'Keller Calibration' tab within the 'Deployment Settings' section. The interface includes a menu bar at the top with options like System, TOS, Diagrams, HPP, MHP1, MHP2, MHP3, MHP4, PHS, RWS, DCC, Generator, Control, Communication, Graphs A & B, and Help. Below the menu, there are sub-tabs: Drilling, Drill Head, Drilling Settings, Hole Selection, Return Water Pump, Sensors, Deployment, and Deployment Settings. The 'Keller Calibration' sub-tab is active, displaying a table with columns for 'Serial Number', 'Offset', and 'Scale'. The 'Serial Number' column has a value of 0, 'Offset' has 4.02, and 'Scale' has 162.43. To the right of the table, there are instructions: 'Select a Serial Number from the list or enter the data directly.' and 'Pre-enter the calibrations into config/deploy_keller_cal.edg.'. On the right side of the screen, there is a status panel titled 'EHWD Control System Software' showing various system parameters: Revision: 1.69, Date: 2006/09/15 22:57:52, PLAYBACK ON (Fri Jan 27 17:01:25 2006), E-Stop Status (System Go!), Heat/Smoke/Fire (Good), SES Status (unknown), TOS Status (Ready), Fuel Level (LL, L, H, HH), Mission Time (0:00:00), and Mission Start Time (0:00:00). There are also buttons for 'Reset Mission Time' and 'Turn-Off TOS Alarm'. At the bottom right, there is a 'Hole ID' section with fields for 'Number' (49) and 'Letter' (unknown).

Screen Tab: TOS ► Hole Selection

On this tab you select the hole/string number, *either* by clicking on the numbered button on the left *or* by entering it in the "Hole ID" field in the lower right hand corner.

The screenshot shows the 'Hole Selection' tab within the 'Deployment Settings' section. The interface is similar to the previous screen, with the same menu bar and sub-tabs. The 'Hole Selection' sub-tab is active, displaying a table with columns for 'Order' and 'Number'. The 'Order' column lists numbers from 1 to 14, and the 'Number' column lists corresponding hole numbers: 58, 67, 66, 65, 73, 74, 80, 79, 48, 57, 47, 46, 56, and 72. To the right of the table, there are instructions: 'Select a Hole Number from the list or enter the Hole ID directly.' and 'Pre-enter the hole numbers into config/drilling_holes.edg.'. Below the instructions, it says 'The holes are listed in the anticipated order.' On the right side of the screen, there is a status panel titled 'EHWD Control System Software' showing various system parameters: Revision: 1.69, Date: 2006/09/15 22:57:52, PLAYBACK ON (Fri Jan 27 17:01:25 2006), E-Stop Status (System Go!), Heat/Smoke/Fire (Good), SES Status (unknown), TOS Status (Ready), Fuel Level (LL, L, H, HH), Mission Time (0:00:00), and Mission Start Time (0:00:00). There are also buttons for 'Reset Mission Time' and 'Turn-Off TOS Alarm'. At the bottom right, there is a 'Hole ID' section with fields for 'Number' (49) and 'Letter' (unknown).

**Distances between devices**

calculate manually and enter on Deployment Settings tab

Distance between Paro and DOM60: $\frac{0.7 + 17}{0.7 + 18.5} = \frac{17.7 \text{ nominal}}{19.2 \text{ actual}}$

Distance between Keller and DOM60: $\frac{1.6 + 31.17 + 1.5}{530.1} = \frac{33.27}{530.1} \text{ nominal}$
 $= \frac{32.93}{530.1} \text{ actual}$

Distance between Paro and Keller: $530.1 - 17.7 = 510.9$

Notes:

There are 60 DOMs on every string.

The nominal spacing between DOMs is 17 m.

The nominal spacing between breakouts is 34 m.

Breakouts (1-30) and DOMs (1-60) are counted from the top.

The Keller is at breakout 15, just above DOM29.

The Paro is at breakout 30, just above DOM59.

(Fun Fact: There used to be a second Paro at breakout 1 on the first four strings)

Pressure conversions

		PSI	mH ₂ O	Atm
1 PSI	=	1	0.70	0.07
1 mH ₂ O	=	1.4	1	0.1
1 atm	=	14.7	10.3	1



Check Sheet

STRING # 48

DATE: 11/6/07

Before Deployment

- ☒ Action: Locate laser ranger for well depth measurements.
- ☒ Action: Locate metric tape measure.
- ☒ Action: Locate one Paro and one Keller, *plus spares* of each.
- ☒ Action: Locate bucket (for cooling of Keller sensor with water/ice mix).
- ☒ Action: Fill bucket with snow and place in heated area to make slush.
- ☒ Action: Locate Setra uphole pressure assembly (sensor + cable).

Deployment Startup

- ☒ Action: Click "Deployment" button under "Tower Mode" on Deployment Settings tab.
- ☒ Action: Select string (=hole) number on Hole Selection tab.
- ☒ Action: Note deployment start time. 12:39 pm

Logbook: Time

- ☒ Action: Click "Reset Mission Time" on the right panel on the deployment screen.
- ☒ Action: Click "Startup" under Deployment Events.



IceCube String Deployment Monitoring

☒ **Action:** Note DDB id number (1, 2, 3, or 4).

17.5 + 15.86

ENTER: DDB# (select button)

Logbook: DDB#

☐ **Action:** Take a well depth measurement with the laser ranger.

ENTER: Well depth [m]

Logbook: Well depth

Problem: shelf @ ~35 m depth,
well is very deep, maybe 70-80 m.
cannot get reading on any of 3 rangers.
Did rope + wood trick, few m resolution.
entering 74 m for now. well depth > 60 m.

☒ **Action:** Reset Payout when DOM60 breaks the plane of the floor.

CLICK: "Reset" button (Top of Hole Reset) on Deployment Settings ► Settings tab.

Logbook: Payout Start value

74 m for now.

☐ **Action:** Get cable mark reading at DOM59.

Logbook: Cable mark [m]

NA

laser range with DOM 60 17.5 m
below floor: 17.5 m, payout is
15.86 → reset

☒ **Action:** Attach Paro at breakout #30. (This is called "Paro2" on the monitoring screen).

Logbook: Paro serial number

☒ **Action:** Click "Paro Attached" under Deployment Events.

☒ **Action:** Measure distance between Paro location and nearest DOM.

Estimate distance to *bottom* DOM by adding n 17-meter segments
(n should be 1 for the Paro since nearest DOM is #59).

$$17 + 0.7 = 17.7$$

ENTER: Distance [m] from Paro to *bottom* DOM (#60)

Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60

☒ **Action:** Get cable mark reading at Paro.

No

Logbook: Cable mark [m]

covered in tape



IceCube String Deployment Monitoring

☒ **Action:** Take Paro air pressure reading just before it breaks the water surface.

ENTER: Ambient pressure [PSI] for Paro

Logbook: Paro2 air pressure

During Deployment

☒ **Action:** Click “Paro In Water” under Deployment Events.

☒ **Action:** Measure curved distance of main cable going around DOM (for at least two DOMs).

Logbook: Straight (vertical) distance for DOM segment, curved cable distance

☒ **Action:** Measure real distance between neighboring DOMs (for every pair) with laser ranger.

Logbook: DOM#'s, distance

☒ **Action:** Put Keller (and one spare) in bucket of water (at near freezing temperature) at least one hour before breakout #15 is reached.

Note: The Keller is not temperature corrected and must therefore be brought to the temperature of the water in the hole (0-2°C) before the air pressure offset is determined.

☒ **Action:** Attach Keller at breakout #15.

ENTER: Keller serial number

Logbook: Keller serial number

☒ **Action:** Click “Keller Attached” under Deployment Events.

☒ **Action:** Measure distance between Keller and nearest DOM.

Estimate distance to *bottom* DOM by adding n 17-meter segments (n should be 31 for Keller since nearest DOM is #29).

ENTER: Distance [m] from Keller to *bottom* DOM (#60)

Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60



IceCube String Deployment Monitoring

☒ **Action:** Get cable mark reading at Keller.

Logbook: Cable mark [m] for Keller

☒ **Action:** Determine Keller air pressure offset before (or just as) Keller hits water.

ENTER: Ambient pressure [PSI] for Keller

Logbook: Ambient Keller pressure

☒ **Action:** Click "Keller In Water" under Deployment Events.

☒ **Action:** Get cable mark reading at top DOM.

Logbook: Cable mark [m] 7'

☒ **Action:** Measure well depth as soon as top DOM is under water.

ENTER: Well depth [m]

Logbook: Well depth [m], measurement method (laser/tape)

Between DOM attachment and String Drop

☐ ^{NA} **Action:** Lower Setra assembly into hole (after top DOM is at least 50 m under the surface).

☐ ^{NA} **Action:** Measure distance between Setra sensor and floor of tower (distance marked on cable).

ENTER: Distance Setra to floor [m]

Logbook: Distance Setra to floor

☒ **Action:** Measure well depth with Setra system and laser ranger and compare.

Logbook: Well depth from Setra [m], well depth from laser [m] 65.6 m (laser)

☐ **Action:** If the two well depth measurements agree, switch from laser to Setra in monitoring system.



During String Drop



Action: Click “String Drop” under Deployment Events.



Action: Measure well depth manually (with laser ranger and/or tape measure).

(if shift lead allows: repeat several times during drop)

ENTER: Well depth [m]

Logbook: Well depth, measurement method (laser/tape)



Action: Read cable marks at regular intervals.

Logbook: Cable mark [m]; depth readings [m] (Paro, Keller); time

End of Deployment



Action: Get final pressure readings from Paro and Keller when final depth has been reached.

Logbook: Pressure readings [PSI]; corrected depths [m] (from screen)



Action: Get final well depth reading (laser and/or Setra).

2431.6

HAS TO BE SIMULTANEOUS WITH FINAL PRESSURE READINGS!

Logbook: Well depth [m] (laser); well depth [m] (Setra)



Action: Note deployment end time.

Logbook: Time



Action: Click “Complete” under Deployment Events.

STRING 48

NAME	DOMID	REMARK	DEPLOYED POSITION
Scream	TP6P1305		60
Childs_Play	UP6P1286		59
Mums	TP6P1231		58
Di_kang_Wang	UP6Y4376		57
Chinese_Fir	TP6P1215		56
Captain_Spaulding	UP6P1290		55
Pampas	TP6P1217		54
Patecatl	UP6Y4362		53
	TP6P1243		52
Babordsgatan	UP6H7510		51
Lei_Ku	TP6Y4253		50
Li_Ning_Yang	UP6Y4278		49
Roslagstullsbacken	TP6H7501		48
	UP6P1302		47
Pauhtun	TP6Y4227		46
Dark_Water	UP6P1270		45
Blair_Witch	TP6P1299		44
Bellflower	UP6P1260		43
Fuxing	TP6Y4473		42
Flowering_Crab_Apple	UP6P1226		41
American_Psycho	TP6P1303		40
Freddy_Krueger	UP6P1250		39
Daisy	TP6P1229		38
Hannibal_Lecter	UP6P1296		37
Shennong	TP6Y4469		36
Nu_Wa	UP6Y4466		35
Carnation	TP6P1249		34
The_Thing	UP6P1294		33
Karluk_River	TP6P1425		32
Kiwalik_River	UP6P1498		31
	TP6P1261		30
Mulchatna	UP6P1506		29
Killik_River	TP6P1505		28
Kantishna_River	UP6P1456		27
Klutina_River	TP6P1465		26
	UP6P1282		25
	TP6P1355		24
Mendenhall_River	UP6P1508		23
	TP6P1517	GOLDEN POS 24	22
	UP6P1516	GOLDEN POS 23	21
	TP6P1515	GOLDEN POS 20	20
	UP6P1288		19
	TP6P1513	GOLDEN POS 18	18
	UP6P1210		17
	TP6P1307		16
Batteriparken	UP6H7516		15
Nenana_River	TP6P1435		14
Meade_River	UP6P1460		13
Noatak_River	TP6P1467		12
Nabesna_River	UP6P1474		11
	TP6P1213		10
	UP6P1344		9
Melozitna_River	TP6P1429		8
KingSalmon_River	UP6P1436		7
	TP6P1273		6
Bergsgatan	UP6H7518		5
Innoko_River	TP6P1473		4
Itkillik_River	UP6P1468		3
Banergatan	TP6H7513		2
	UP6P1248		1
Matanuska_River	TP6P1477		
	TP6Y4447		
	UP6H7506		
	UP6P1262		



String Installation Traveler

Surface Cable# : 48	Start date: 05-06 season
Length (m) : 599	
Surface to DOM Cable# : 17	Start date: 1/14/07

	Process Step	Doc. no. reference	Tech initials	Date Completed	Comments
1	Visual Inspection of Cables at Pole	9400-0006-QLP	MK	1/14/07	

Surface Cable Assembly Inspection

Pass

☒

Fail

☐

By:

Surface to DOM Cable Assembly Inspection

Pass

☒

Fail

☐

By:

2	Trench Surface Cable Assembly (SCA)	9400-0006-QLP	MK		05-06 season
3	Install SCA into Surface Junction Box (SJB)	9400-0006-QLP	MK		05-06 season
4	Install SCA into ICL	9400-0075-PLN	MK	1/14/07	
5	Complete IceTop FCU Power and Data Installation Procedure	9400-005-QLP			
6	Verify Connectivity of IceTop DOMs with Quad Connectivity Tester (QCT)		MK	1/10/07	
7	Pre-deployment Inspection Procedure		MK	1/14/07	
8	S2D Cable into SJB installation	9400-0007-QLP	MK	1/16/07	
9	Wet Connector Testing of Quads		MK	1/16/07	
10	QCT Testing of Quads		MK	1/16/07	
11	SJB Final Inspection Complete (Ok to Bury)	9400-0007-FRM	MK	1/21/07	
12	Handoff to IceCube C & V Team		MK	1/16/07	



String Installation Traveler

String QCT and Wet Connector Test Form

String #

48

Name of Tester:

Mike Klerst

QCT Results

of DOMs (0, 1, 2)

Wet Connector Test Results (micro Amps)

Quad name	# of DOMs WP0	# of DOMs WP1	Pass/Fail	J	L	M	K	Pass/Fail	Recheck Pass/Fail
Q2	2	2	P					P	
Q3	2	2	P					P	
Q4	2	2	P					P	
Q5	2	2	P					P	
Q6	2	2	P					P	
Q7	2	2	P					P	
Q8	2	2	P					P	
Q9	2	2	P					P	
Q10	2	2	P					P	
Q11	2	2	P					P	
Q12	2	2	P					P	
Q13	2	2	P					P	
Q14	2	2	P					P	
Q15	2	2	P					P	
Q16	2	2	P					P	
IceTop Quads									
ITQ1	1	1	P						
ITQ2	1	1	P						

Verified on

Tech Initials

Comments

Service Quads	Device Connected	Verified on	Tech Initials	Comments
Q1				
Q17				
Q18				
Q19				
Q20				